

Example S-SAD phasing: requirements for data collection

Data collection:
Accurate
Redundant
Independent

Scan	Scan type	ω	ϕ	2θ
1	180° ω	0°-180°	0°	0°
2	180° ω	30°-210°	0°	30°
3	180° ω	0°-180°	60°	0°
4	360° ω	0°	0°-360°	0°
5	180° ω	0°-180°	120°	0°

Anomalous redundancy calculated by strategy generator: ~30
Total exposure time (60 s per image): 30 h

Table 8-8 Strategy for highly redundant data collection. The table entries contain the scan ranges and diffractometer angle settings for a highly redundant data collection strategy for the collection of anomalous data required for native sulfur single-wavelength anomalous diffraction (S-SAD) phasing for VTA1 (Laue symmetry 4/mmm).⁷³

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Example S-SAD phasing of a small protein

Anomalous data from native sulfur in disulfide bridges in VTA1, the small plant toxin in mistletoe.

Figure 10-28 Flow of S-SAD phasing. The basic steps of S-SAD phasing are neatly arranged in the HK2MAP GUI. Analysis and preparation of anomalous difference data, search for the anomalous heavy atoms, and determination and extension of phases.

Figure 10-29 Empirical resolution cutoff for S-SAD phasing. The plot shows the signal level of the anomalous amplitude differences for the high redundancy anomalous data collected at the Cu wavelength. In the case of the high resolution data collected at the high energy wavelength of 0.8340 Å (red graph) practically no more S anomalous signal is measurable. An empirically well determined high resolution cutoff is around the point where the anomalous signal-to-noise ratio drops below 1.3.

Data cutoff is important for getting any solution.

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Multisolution landscape with SHELXD

Figure 10-30 Effect of resolution truncation on heavy atom solution. Anomalous difference data are sensitive to noise, and need to be truncated at an optimal high resolution cutoff. A clear solution (right panel) is distinguished from a poor or wrong solution (left panel) by a discrete solution landscape indicated by a clear drop in occupancy after a number of correct high occupancy sites were found. Note that a high number of trials may be necessary to find all sulfur sites with SHELXD.

Figure 10-31 Multisolution landscape. The plot shows the correct solution (right panel) and the incorrect solution (left panel). The correct solution is distinguished from the incorrect solution by a sharp drop in occupancy after a number of correct high occupancy sites were found. Note that a high number of trials may be necessary to find all sulfur sites with SHELXD.

Sharp drop in occupancy after expected number of correct atoms is a sign of correct solution.

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First maps determine substructure handedness

Figure 10-32 Stages of phase ambiguity resolution and enantiomorph selection. While the phase ambiguity is resolved already in the first step by a fast density estimation algorithm, the initial substructure handedness is determined by trying both enantiomorphs, correct and inverted, and then the correct one is selected. The top row shows the maps at 2.5 Å after the initial ambiguity resolution, but no further density improvement for both enantiomorphs. The middle row shows the correct enantiomorph (D) appears less noisy and shows the expected "sulfur" density (red and sulfur is correct position). The center row (E) shows further improvement by spheres of influence solvent modification for the correct substructure enantiomorph (D), but still no phase extension beyond 2.5 Å has been attempted. The bottom row (F) shows the maps after phase extension to 1.25 Å in 20 cycles of phase extension. The clearly can distinguish side chain shapes and atoms begin to be visible at this resolution (F). As it may not be clear for the beginner to distinguish correct from your maps with the unaided eye, attention to the map statistics (Figure 10-33) is really important.

The wrong substructure enantiomorph will not yield an interpretable map

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Quantitative indicators of a 'good' map

Figure 10-32 Map contrast and final map correlation coefficient. The map contrast is a key indicator in the discrimination between correct and inverted heavy atom substructure enantiomorph (left panel). For the final map, the map correlation coefficient is an indicator for the resulting map quality. Given that the map correlation coefficient is approaching 0.95 over large parts of the map including the high resolution shells, we expect an exceptional experimental electron density map.

The map resulting from the correct substructure enantiomorph will show significantly better map contrast and map correlation coefficients.

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Visual appearance of a good map

Figure 10-33 S-SAD experimental electron density of VTA1 at 1.25 Å resolution. As expected from the map correlation coefficient, which was above 0.9 for the high resolution reflections, we obtain an experimental map of outstanding quality. The delineation of protein and solvent is clear, and even discrete solvent molecules are visible. In the overview panel we also recognize high density of the S atoms in an S-S bridge, and from a helix viewed in cross section compare Figure 12-28) protrudes a tyrosine residue with a nice hole in the aromatic ring. Because protein crystallographers tend to present holes in phenyl rings of experimentally phased maps with great pride, we share the detail view in the right panel.

Clear contrast, good connectivity, and distinct protein features. This is an excellent experimental phase map. It does not have any model bias.

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